

01-19-00

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PATENT

Docket No. 1232-4607Express Mail Label No. EJ606954024US

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

UTILITY APPLICATION AND APPLICATION FEE TRANSMITTAL (1.53(b))

ASSISTANT COMMISSIONER FOR PATENTS
Box Patent Application
Washington, D.C. 20231

Sir:

Transmitted herewith for filing is the patent application of

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Japan

For: IMAGE SENSING APPARATUS AND IMAGE PROCESSING METHOD
THEREFOR

Enclosed are:

☒ 48 page(s) of specification, 1 page(s) of Abstract, 23 page(s) of claims

☒ 21 sheets of drawing ☒ formal ☐ informal

☐ Page(s) of Declaration and Power of Attorney

- ☐ Unsigned
☐ Newly Executed
☐ Copy from prior application

☐ Deletion of inventors including Signed Statement under 37 C.F.R. § 1.63(d)(2)

☒ Incorporation by Reference: The entire disclosure of the priority application(s) identified below, is considered as being part of the disclosure of the accompanying application and is incorporated herein by reference.

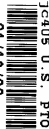
☐ Microfiche Computer Program (Appendix)

☐ page(s) of Sequence Listing

- ☐ computer readable disk containing Sequence Listing
☐ Statement under 37 C.F.R. § 1.821(f) that computer and paper copies of the Sequence Listing are the same

☒ Claim for Priority Japanese Application Nos. 11-012339 filed 1/20/99; 11-012338 filed 1/20/99; 11-053383 filed 3/1/99; and 11-053384 filed 3/1/99

01/18/00



- ☐ Certified copy of Priority Document(s)
- ☐ English translation documents
- ☐ Information Disclosure Statement
- ☐ Copy of ___Cited references w/ English Abstracts
- ☐ Copy of PTO-1449 filed in parent application serial No. _____
- ☐ Preliminary Amendment
- ☒ Return receipt postcard (MPEP 503)
- ☐ Assignment Papers (assignment cover sheet and assignment documents)
- ☐ A check in the amount of \$40.00 for recording the Assignment.
- ☐ Assignment papers filed in parent application Serial No. _____
- ☐ Certification of chain of title pursuant to 37 C.F.R. § 3.73(b).
- ☐ This is a ☐ continuation ☐ divisional ☐ continuation-in-part (C-I-P) of prior application serial no. _____.
- ☐ Cancel in this application original claims _____ of the parent application before calculating the filing fee. (At least one original independent claim must be retained for filing purposes.)
- ☐ A preliminary Amendment is enclosed. (Claims added by this Amendment have been properly numbered consecutively beginning with the number following the highest numbered original claim in the prior application.
- ☐ The status of the parent application is as follows:
- ☐ A Petition For Extension of Time and a Fee therefor has been or is being filed in the parent application to extend the term for action in the parent application until _____.
- ☐ A copy of the Petition for Extension of Time in the co-pending parent application is attached.
- ☐ No Petition For Extension of Time and Fee therefor are necessary in the co-pending parent application.
- ☐ Please abandon the parent application at a time while the parent application is pending or at a time when the petition for extension of time in that application is granted and while this application is pending has been granted a filing date, so as to make this application co-pending.
- ☐ Transfer the drawing(s) from the patent application to this application.
- ☐ Amend the specification by inserting before the first line the sentence:
This is a ☐ continuation ☐ divisional ☐ continuation-in-part of co-pending application Serial No. _____ filed _____.

I. CALCULATION OF APPLICATION FEE (For Other Than A Small Entity)

	Basic Fee			
	Number Filed		Number Extra	Rate \$ 690.00
Total Claims	61	-20=	41	x\$18.00 \$ 738.00
Independent Claims	11	- 3=	8	x78.00 \$ 624.00
Multiple Dependent Claims				
	[] yes		Additional Fee =	\$260.00
	[X] no		Add'l Fee =	NONE \$ 0

Total: \$2,052.00

[] A statement claiming small entity status is attached or has been filed in the above-identified parent application and its benefit under 37 C.F.R. § 1.28(a) is hereby claimed. Reduced fees under 37 C.F.R. § 1.9(F) (50% of total) paid herewith \$ _____.

[X] A check in the amount of \$2,052.00 for payment of the application filing fees is attached.

[] Charge Fee(s) to Deposit Account No. 13-4500. Order No. _____. A DUPLICATE COPY OF THIS SHEET IS ATTACHED.

[X] The Assistant Commissioner is hereby authorized to charge any additional fees which may be required for filing this application, or credit any overpayment to Deposit Account No. 13-4500, Order No. 1232-4607. A DUPLICATE COPY OF THIS SHEET IS ATTACHED.

Respectfully submitted,

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TITLE OF THE INVENTION

IMAGE SENSING APPARATUS AND IMAGE PROCESSING METHOD THEREFOR

5

BACKGROUND OF THE INVENTION

The present invention relates to an image sensing apparatus such as a digital camera or digital video camera or the like, and an image processing method for the image sensing apparatus.

A conventional single-plate color digital camera is a lens-integrated system, and is generally incapable of exchanging a lens. For this reason, an optical low pass filter and infrared ray (IR) filter or the like are provided before a CCD, which generates image signals according to light passing through the lens, thereby achieving a certain degree of effectiveness in reducing moiré or pseudo colors (erroneous colors).

However, in a case of a camera which allows lens exchange, an IR filter can be provided before a CCD by forming a thin film on a glass surface of the CCD. However, securing space for an optical low pass filter before a CCD causes to increase the size of the camera body. Furthermore, although such optical low pass filter can reduce moiré or pseudo colors to a certain

degree, a problem arises in that spatial frequency of an image decreases, and as a result, the image loses exact-focused characteristic such as that obtained in silver chloride photographs. Because of the above
5 reason, the importance of an optical system without an optical low pass filter is increasing.

Furthermore, even if such optical low pass filter is provided, in a case of a digital camera employing a single-plate CCD, pseudo colors are still generated
10 when color interpolation is performed. As exemplified by the Bayer pattern, when a number of R (red) and B (blue) color components is less than that of G (green) color components, the gap between these pixels becomes large, and this causes generation of pseudo colors in
15 color interpolation. Furthermore, a method of generating three color planes with a digital filter or the like is available as a conventional color interpolation. However, since the order of the digital filter is limited, original image data resolution
20 cannot be sufficiently expressed.

In view of the above, conventionally proposed is to perform image processing, particularly color interpolation, disclosed in US Patent No. 5,373,322 or No. 5,629,734, to obtain high resolution image data.
25 This technique is effective to reduce pseudo colors, but not effective for moiré .

Even with the conventional technique, isolated pseudo colors, generated particularly around small characters or the like, cannot completely be eliminated. In view of this, it is proposed to convert color space, e.g., from RGB to $L^*a^*b^*$, by an application program operating in a computer, and perform processing such as filtering on a^* and b^* to remove pseudo colors.

However, even if such conventional technique is employed, pseudo colors in color interpolation cannot completely be eliminated. This is further described below.

As shown in Fig. 19, if vertical white lines are exposed to green (G) and red (R) lines of a CCD at pixel pitch and conventional color interpolation is performed, red (R) and yellow (Y) vertical stripes are obtained (in Fig. 19, hatching portion indicates black where data is 0). Similarly, as shown in Fig. 20, if vertical white lines are exposed to green (G) and blue (B) lines of a CCD at pixel pitch and color interpolation is performed, blue (B) and cyan (C) vertical stripes are obtained. Note that even if the stripes in Figs. 19 and 20 are horizontal instead of vertical, the same results, i.e., red (R) and yellow (Y) stripes or blue (B) and cyan (C) stripes, are obtained.

Furthermore, as another pattern, if white pixels

having a checker flag pattern shown in Fig. 21 are exposed to R and B of a CCD and color interpolation is performed, a magenta (M) image is obtained despite the original white color. Still further, if white pixels
5 having a checker flag pattern shown in Fig. 22 are exposed to G of the CCD and color interpolation is performed, a green (G) image is obtained despite the original white color.

In order to remove such pseudo colors, the color
10 space is converted from RGB to, for instance, $L^*a^*b^*$ and filtering is performed on each of the a^* and b^* color spaces by an application program operating in a personal computer. However, in the case of checker flag patterns shown in Figs. 21 and 22, a low frequency
15 image of green cannot be distinguished from that of magenta, making it impossible to determine pseudo colors. If the frequency band of color difference is forcefully limited for JPEG compression, a dull (blurred) image is obtained. As a result, although the
20 level of pseudo colors is reduced, the pseudo color components are spread out to the peripheral pixels, causing problems.

Furthermore, if the image data is compressed according to JPEG or the like without performing above-
25 described pseudo color removing processing, block noise or the like may be caused. Moreover, if the frequency

band of color difference is forcefully limited for JPEG
compression, an image becomes blurred. As a result,
although the level of pseudo colors is reduced, the
pseudo color components are spread out to the
5 peripheral pixels, causing problems. In order to
eliminate such pseudo colors, it is ideal to employ a
three-plate camera using three image sensing devices
for each color component. However, such construction
increases the size and cost of the camera.

10

SUMMARY OF THE INVENTION

The present invention is made in consideration of
the above situation, and has as its object to provide
an image sensing apparatus capable of reducing pseudo
15 colors generated by color interpolation, and an image
processing method for the image sensing apparatus.

Furthermore, another object of the present
invention is to provide an image sensing apparatus
which can reduce pseudo colors without increasing the
20 size or cost of the image sensing apparatus, and an
image processing method for the image sensing apparatus.

Furthermore, another object of the present
invention is to provide an image sensing apparatus
which can reduce pseudo colors with relatively a simple
25 construction, and an image processing method for the
image sensing apparatus.

Furthermore, Another object of the present invention is to provide an image sensing apparatus which can reduce pseudo colors in isolated pixels with relatively a simple construction, and an image
5 processing method for the image sensing apparatus.

In order to attain the above-described objects, the image sensing apparatus according to the present invention has the following configuration.

More specifically, the present invention provides
10 an image sensing apparatus comprising: an image sensing device; image forming means for forming an image on said image sensing device; A/D conversion means for converting an image signal outputted by said image sensing device into a digital signal; color
15 interpolation means for performing color interpolation on the digital signal converted by said A/D conversion means and generating image data on a plurality of color planes; color space conversion means for converting a color space of the plurality of color planes to a color
20 space of another colorimetric system; and isolated point removing means for reducing a pseudo color, generated by said color interpolation means, by controlling a color difference signal converted by said color space conversion means.

25 Furthermore, the present invention provides an image sensing apparatus comprising: an image sensing

device; image forming means for forming an image on
said image sensing device; A/D conversion means for
converting an image signal outputted by said image
sensing device into a digital signal; color

- 5 interpolation means for performing color interpolation
on the digital signal converted by said A/D conversion
means and generating image data on a plurality of color
planes; pseudo color removing means for reducing a
pseudo color component included in image data, on which
10 color interpolation is performed by said color
interpolation means; color space conversion means for
converting a color space of the plurality of color
planes, where a pseudo color is reduced by said pseudo
color removing means, to a color space of another
15 colorimetric system; and compression means for
compressing image data where color space is converted
by said color space conversion means.

Herein, the isolated point removing means
includes an isolated point removing filter which
20 replaces a value of a pixel of interest with a
substantial median pixel value of peripheral pixels of
the pixel of interest. Also, the isolated point
removing filter includes a median value filter or
median filter.

25 Moreover, the color interpolation means generates
image data in R, G and B planes.

Further, the color space conversion means may convert RGB color space to YUV color space.

Still further, the color space conversion means may convert RGB color space to Y, R-Y, B-Y color space.

5 Still further, the color space conversion means may convert RGB color space to G, R-G, B-G color space.

Moreover, the image forming means includes an infrared ray filter, or an infrared ray filter and optical low pass filter.

10 Furthermore, the image processing method for the image sensing apparatus according to the present invention has the following steps.

More specifically, the present invention provides an image processing method for an image sensing apparatus which includes an image sensing device and generates an image signal corresponding to an image formed on the image sensing device, comprising: an A/D conversion step of converting an image signal outputted by the image sensing device into a digital signal; a
15 color interpolation step of performing color interpolation on the digital signal converted in said A/D conversion step and generating image data on a plurality of color planes; a separation step of separating the image data in the plurality of color
20 planes into luminance data and color difference data; an extraction step of extracting a high frequency
25

component from the luminance data separated in said separation step; and a pseudo color removing step of reducing a pseudo color generated in said color interpolation step, in accordance with the high frequency component of the luminance data extracted in said extraction step and hue data obtained from the color difference data.

Herein, the pseudo color removing step comprises: a determination step of determining whether or not the high frequency component of the luminance data and the hue data fall within a color range of the pseudo color; and a step of reducing a value of the color difference data, determined to be within the color range in said determination step.

Moreover, in the color space conversion step, it is preferable that the color space be converted to YUV, or Y, R-Y, B-Y, or G, R-G, B-G color space.

Moreover, the image processing method may further comprise a step of removing a high frequency component from a color signal, from which the pseudo color is removed in said pseudo color removing step.

Herein, the color range of the pseudo color includes a color area from red to yellow, and a color area from blue to cyan.

Other features and advantages of the present invention will be apparent from the following

description taken in conjunction with the accompanying drawings, in which like reference characters designate the same or similar parts throughout the figures thereof.

5

BRIEF DESCRIPTION OF THE DRAWINGS

The accompanying drawings, which are incorporated in and constitute a part of the specification, illustrate embodiments of the invention, and together with the description, serve to explain the principles of the invention.

Fig. 1 is a block diagram showing, mainly, a construction of an image processing unit of a digital camera according to the first embodiment of the present invention;

Figs. 2A and 2B are conceptual views explaining pseudo color removal according to embodiments of the present invention;

Fig. 3 is a block diagram showing, mainly, a construction of an image processing unit of a digital camera according to the second embodiment of the present invention;

Fig. 4 is a block diagram showing, mainly, a construction of an image processing unit of a digital camera according to the third embodiment of the present invention;

Fig. 5 is a block diagram showing, mainly, a construction of an image processing unit of a digital camera according to the fourth embodiment of the present invention;

5 Fig. 6 is a block diagram showing, mainly, a construction of an image processing unit of a digital camera according to the fifth embodiment of the present invention;

Fig. 7 is a block diagram showing a configuration
10 of a pseudo color removing processor according to the fifth embodiment;

Fig. 8 is a block diagram showing a configuration after the gamma converter shown in Fig. 6, for a digital camera according to the sixth embodiment of the
15 present invention;

Fig. 9 is a block diagram showing, mainly, a construction of an image processing unit of a digital camera according to the seventh embodiment of the present invention;

20 Fig. 10 is a conceptual view for explaining color interpolation according to embodiments of the present invention;

Fig. 11 is an explanatory diagram showing a construction of a high frequency filter according to
25 embodiments of the present invention;

Fig. 12 is a graph explaining processing of a

pseudo color suppression unit according to embodiments of the present invention;

Fig. 13 shows a hue range of pseudo colors in pseudo color suppression processing according to 5 embodiments of the present invention;

Fig. 14 is a flowchart explaining pseudo color removing processing according to the seventh and eighth embodiments of the present invention;

Fig. 15 is a block diagram showing, mainly, a 10 construction of an image processing unit of a digital camera according to the eighth embodiment of the present invention;

Fig. 16 is a block diagram showing a construction of an image processing unit of a digital camera 15 according to the ninth embodiment of the present invention;

Fig. 17 shows a hue range of pseudo colors in pseudo color suppression processing according to the ninth embodiment of the present invention;

Fig. 18 is a block diagram showing a construction of an image processing unit of a digital camera 20 according to the tenth embodiment of the present invention;

Fig. 19 is a conceptual view explaining a general 25 pseudo color generation process;

Fig. 20 is a conceptual view explaining a general

pseudo color generation process;

Fig. 21 is a conceptual view explaining a general
pseudo color generation process; and

Fig. 22 is a conceptual view explaining a general
5 pseudo color generation process.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

Preferred embodiments of the present invention
will be described in detail in accordance with the
10 accompanying drawings.

[First Embodiment]

Fig. 1 is a block diagram showing, mainly, a
construction of an image processing unit of a digital
camera according to a first embodiment of the present
15 invention.

Light 1, incident upon the digital camera
according to the first embodiment, passes through lens
2, then the amount of the light is adjusted by a
diaphragm 3, and an image sensing device 5 (hereinafter
20 referred to as a CCD), e.g., CCD or CMOS, is exposed
while a shutter (not shown) is open. Before the light
1 is incident upon the CCD 5, an optical low pass
filter 20 limits a spatial frequency of the light 1 to
reduce moiré in a way that an optical area of a long
25 wavelength is cut off by an infrared ray (IR) filter 4
so that the CCD 5 does not detect light in the infrared

region. By the light incident upon the CCD 5, the amount of electric charge corresponding to the intensity of light is accumulated in the CCD 5. The amount of electric charge is amplified by a
5 predetermined gain by a CDS-AGC 6, and converted to digital data by an A/D converter 7. Image data converted to digital data in the foregoing manner is transferred to a white balance circuit 8 where R, G and B gains are adjusted. Then, by a color interpolator 9,
10 the image data is generated in, for instance, three color (R, G and B) planes. The image data expressed in the R, G and B planes are then transferred to a masking processor 10 where adjustment is made for the hue of the R, G and B colors. Then, a gamma converter 11
15 performs necessary processing for displaying an image on a display or the like.

Next, compression according to JPEG or the like is performed on the image data since the data in the R, G and B color planes has a large amount of data.

20 Herein, first, an RGB/YUV converter 12 converts the image data from R, G and B signals to Y color difference signals. For instance, R, G and B data are respectively converted to Y, U and V as follows:

25
$$Y = 0.29900 \times R + 0.58700 \times G + 0.11400 \times B \quad (1)$$

$$U = -0.16874 \times R - 0.33126 \times G + 0.50000 \times B \quad (2)$$

$$V = 0.50000 \times R - 0.41869 \times G - 0.08131 \times B \quad (3)$$

Next, with respect to U and V, each representing a color difference signal, a pseudo color generated by color interpolation is reduced by median filters 13a and 13b. Low pass filters (LPF) 14a and 14b remove high frequency components to limit the band. Then, a thinning circuit 15 performs thinning processing which complies with a predetermined compression method, e.g., from Y:U:V = 4:4:4 to Y:U:V = 4:2:2 or Y:U:V = 4:1:1. Then, a compression circuit 16 adopting JPEG or the like performs compression.

Figs. 2A and 2B explain the principle of processing performed by the median filters 13a and 13b according to the first (and subsequent) embodiment. Herein, Fig. 2A shows 3 × 3 pixels peripheral to a pixel of interest, and Fig. 2B shows a graph of pixel values arranged in the ascending order.

Herein, for instance, 3 × 3 pixels peripheral to a pixel of interest a*22 are extracted, and the pixel values (color difference values) are arranged in the ascending order. Then, the value "20" of the pixel of interest is replaced with the value "10" of a*33, which is the substantial median value of the nine pixels. Such processing is performed by the median filters 13a and 13b, serving as isolated point removing filters.

By this, isolated pseudo colors can be reduced without largely decreasing resolution. Note that since the configuration of the median filter is well known (e.g., disclosed in Japanese Patent Application Laid-Open No. 5-233804 or No. 5-12437), detailed description thereof will be omitted.

As has been described above, according to the first embodiment, a color space of an inputted image signal is converted from RGB to YUV color space, and an isolated pixel is removed from color difference signals U and V of the YUV signal by the median filter or the like. By virtue of this, pseudo colors generated by color interpolation can be reduced.

[Second Embodiment]

In the above-described first embodiment, color conversion from RGB to YUV color space is performed and pseudo color reduction processing is performed in the YUV color space before image compression is performed according to JPEG or the like. However, pseudo color reduction processing is not necessarily performed in YUV color space, but may be performed in another color space.

According to the second embodiment of the present invention, pseudo color removal is performed by a median filter, after a color space of input image data

is converted from RGB color space to Y, R-Y, B-Y color space.

Fig. 3 is a block diagram showing a construction of an image processing unit of a digital camera according to the second embodiment. For the components that are common to the construction shown in Fig. 1, the same reference numerals are assigned and description thereof will be omitted. The second embodiment largely differs from the foregoing first embodiment in that the second embodiment does not necessitate JPEG compression and that the YUV conversion can be eliminated since the pseudo-color-removed image data is stored in a memory 19. Therefore, the construction of the image processing unit can be made simple, which contributes to the effect of the second embodiment. This is also applicable to a case of performing compression according to JPEG or the like.

According to the second embodiment, in order to achieve reduction in the amount of calculation compared to the case of converting data from RGB to YUV color space, image data is converted from RGB color space to Y, R-Y, B-Y color space by, for instance, using a Y, R-Y, B-Y converter 17a.

Herein, for instance, color space conversion is executed in the following manner:

$$Y = 0.29900 \times R + 0.58700 \times G + 0.11400 \times B \quad (4)$$

$$R-Y = R-Y \quad (5)$$

$$B-Y = B-Y \quad (6)$$

5 Then, the median filters 17b and 17c respectively
executes median filtering of the R-Y signal and B-Y
signal. Herein, the equation can be further simplified
as follows to obtain luminance signal Y, color
difference signals R-Y and B-Y:

10

$$Y = R + 2 \times G + B = Y_e \quad (7)$$

$$R-Y = R-Y_e \quad (8)$$

$$B-Y = B-Y_e \quad (9)$$

15 In this case, R-Y_e and B-Y_e are calculated with a
luminance signal Y_e which is a simplified (approximate)
form of the luminance signal Y. By executing median
filtering respectively to R-Y_e and B-Y_e, pseudo colors
can be removed. Although the resultant values are
20 slightly different from values of Y, R-Y and B-Y, a
similar effect is achieved and calculation can be
performed easily. Next, an RGB converter 17d
respectively converts the Y, R-Y and B-Y signals back
to R, G and B signals. The image data represented by R,
25 G and B signals is subjected to masking by a masking
processor 10 and to a gamma conversion by a gamma

converter 11, and then stored in the non-volatile memory 19.

[Third Embodiment]

5 In the above-described second embodiment, the luminance signal Y is consciously calculated from R, G and B signals. However, in image processing, G signal of the R, G and B may substitute for the luminance signal Y.

10 The third embodiment is characterized by employing G, R-G and B-G signals instead of Y, R-Y and B-Y signals employed in the second embodiment, and executing median filtering to R-G and B-G signals respectively.

15 Fig. 4 is a block diagram showing a construction of an image processing unit of a digital camera according to the third embodiment of the present invention. For the components that are common to the construction shown in Fig. 3, the same reference
20 numerals are assigned and description thereof will be omitted.

According to the third embodiment, the amount of calculation is reduced further when compared against the case of converting R, G and B signals to luminance
25 signal Y and color difference signals R-Y and B-Y. The G, R-G, B-G converter 18a generates G, R-G and B-G

signals from R, G and B signals using the following equations:

$$Y = G \quad (10)$$

5 $R-Y = R-G \quad (11)$

$$B-Y = B-G \quad (12)$$

The median filters 18b and 18c respectively execute filtering to the R-G and B-G signals, thereby
10 removing pseudo colors generated by color interpolation. Then, the RGB converter 18d converts the G, R-G and B-G signals back to RGB signals, which are then subjected to the masking processor 10 and gamma converter 11, and then stored in the non-volatile memory 19.

15 As has been described above, since the third embodiment employs G signal in place of luminance signal Y, pseudo color reduction can be realized with a less amount of calculation, although there is a possibility that luminance components of the RGB
20 signals may be influenced by the result of median filtering.

[Fourth Embodiment]

The above-described first to third embodiments
25 describe the case of employing an optical low pass filter before the CCD 5. Note that the configuration

before the CCD 5 is not shown in Figs. 3 and 4.

The fourth embodiment describes a case where no problem arises even though the optical system does not comprise such optical low pass filter.

5 Fig. 5 is a block diagram showing a construction of an image processing unit of a digital camera according to the fourth embodiment of the present invention. For the components that are common to the construction shown in Fig. 1, the same reference
10 numerals are assigned and description thereof will be omitted. The fourth embodiment is characterized in that the IR filter 4 for cutting infrared rays is provided before the CCD 5, and that the optical low pass filter 20 employed in Fig. 1 is removed. The
15 configuration after the CCD 5 is the same as that shown in block diagram of Fig. 1.

However, when the optical low pass filter 20 is removed, pseudo colors are generated more than the case of including the optical low pass filter 20. In view
20 of this, the number of elements in median filters 130a and 130b in the fourth embodiment is increased from the number of elements "9" of the median filters according to first to third embodiments. By this, the median filtering can be executed in a wider area, and pseudo
25 colors can be reduced.

Accordingly, since the fourth embodiment is

realized by simply mounting the IR filter 4 on the glass surface of the CCD 5, the apparatus main body can be made small and cost reduction can be achieved. In addition, image signals of high resolution can be
 5 obtained.

For the isolated point removing filter, filtering called smoothing (Edge Preserving Smoothing), which preserves edges, may be employed besides the above-described median filter. More specifically, a window
 10 $W(i, j)$ is set with a pixel $f(x, y)$ as its center, and an output $g(x, y)$ is calculated. Assuming that the window size is $m \times n$, the following equation stands:

$$g(x, y) = \sum_{i=-1}^m \sum_{j=-1}^n w(i, j) \times f(x-i, y-j)$$

15 For instance, assuming a matrix M in which data "1" is arranged in 3×3 matrix, the following equation stands:

$$W = M/9$$

20

For an alternative isolated point removing filter, another smoothing (Maximum Homogeneity Smoothing) which preserves edges may be employed. This smoothing enables selection of a most uniform area in the

neighborhood of a pixel. When the weight coefficient F_i is defined as follows:

weight coefficient $F_i = \{\min(\sigma_i)\} / \sigma_i$

- 5 where an average value of each block is μ_i ,
distribution is σ_i , and m (arbitrary),

the output $g(x, y)$ is obtained in the following manner:

$$g(x, y) = \sum_{i=1}^8 \{F_i^m\} \mu_i / \sum_{i=1}^8 F_i^m$$

10

Besides the above, filtering called hysteresis smoothing may be employed. More specifically, a hysteresis characteristic is produced for a data value, and noise is absorbed by the hysteresis characteristic.

- 15 Any of the aforementioned filters may be used as long as interpolation or smoothing is performed by using outputs of peripheral pixels of an isolated point having a pixel value largely different from peripheral pixel values.

20

[Fifth Embodiment]

Fig. 6 is a block diagram showing, mainly, a construction of an image processing unit of a digital camera according to the fifth embodiment of the present

invention. For the components that are common to the foregoing embodiments, the same reference numerals are assigned.

Light 1, incident upon the digital camera
5 according to the fifth embodiment, passes through the lens 2, then the amount of the light is adjusted by the diaphragm 3, and the image sensing device 5 (hereinafter referred to as a CCD), e.g., CCD or CMOS, is exposed while a shutter (not shown) is open. Before
10 the light 1 is incident upon the CCD 5, a frequency region of a long wavelength is cut off by the IR filter 4 so that the CCD 5 does not detect light in the infrared region. By the light incident upon the CCD 5, the amount of electric charge corresponding to the
15 intensity of light is accumulated in the CCD 5. The amount of electric charge is amplified by a predetermined gain by the CDS-AGC 6, and converted to digital data by the A/D converter 7. Image data converted to digital data in the foregoing manner is
20 transferred to the white balance circuit 8 where R, G and B gains are adjusted. Then, by the color interpolator 9, the image data is generated in, for instance, three color (R, G and B) planes. The image data expressed in the R, G and B planes are then
25 transferred to the masking processor 10 where adjustment is made for the hue of the R, G and B colors.

Then, the gamma converter 11 performs necessary processing for displaying an image on a display or the like.

Next, a pseudo color removing processor 21
5 reduces pseudo colors generated by color interpolation of the color interpolator 9. Further, compression processing according to JPEG or the like is performed on the image data since the data in the R, G and B color planes has a large amount of data. Herein, first,
10 the RGB/YUV converter 12 converts the image data from R, G and B signals to Y color difference signal, and with respect to each of the color difference signals U and V, the LPF 14a and 14b respectively perform low pass filtering to limit the band. Then, the thinning
15 circuit 15 performs thinning processing which complies with a predetermined compression method, e.g., from $Y:U:V = 4:4:4$ to $Y:U:V = 4:2:2$ or $Y:U:V = 4:1:1$. Then, a JPEG compression circuit 16 performs compression according to JPEG.

20 Fig. 7 is a block diagram showing a configuration of the pseudo color removing processor 21 according to the fifth embodiment.

Assume that image data is generated in R, G and B planes by the color interpolator 9. The RGB/XYZ
25 converter 21a converts image data from RGB color space to XYZ color space. The conversion is executed by the

following equations (13) to (15):

$$X = 2.7689 \times R + 1.7517 \times G + 1.1302 \times B \quad (13)$$

$$Y = 1.0000 \times R + 4.5907 \times G + 0.0601 \times B \quad (14)$$

$$5 \quad Z = 0.0000 \times R + 0.0565 \times G + 5.5943 \times B \quad (15)$$

Then, XYZ/L*a*b* converter 21b converts the image data from XYZ color space to L*a*b* color space. The conversion is executed by the following equations (16) to (18):

$$L^* = 116 (Y/Y_0)^{1/3} - 16 (Y/Y_0 > 0.008856) \quad (16)$$

$$a^* = 500 [(X/X_0)^{1/3} - (Y/Y_0)^{1/3}] \quad (17)$$

$$b^* = 200 [(Y/Y_0)^{1/3} - (Z/Z_0)^{1/3}] \quad (18)$$

X_0 , Y_0 and Z_0 represent tristimulus values of the perfect diffuse surface.

Herein, median filters 21c and 21d, each serving as an isolated point filter, execute median filtering (median value filtering) respectively to a^* and b^* of the L*a*b*.

Since the principle of the processing performed by the median filters 21c and 21d is the same as the aforementioned description shown in Figs. 2A and 2B, description thereof will not be provided herein.

Then, L*a*b*/XYZ converter 21e converts image

data from $L^*a^*b^*$ color space to XYZ color space.

Finally, XYZ/RGB converter 21f converts the image data from XYZ color space to RGB color space. By this,

median filtering can be executed only in a color space

5 that gives small influence to the luminance

(resolution). Therefore, the decrease in resolution of an image can be prevented.

[Sixth Embodiment]

10 Fig. 8 is a block diagram showing a configuration according to the sixth embodiment of the present invention.

In the foregoing fifth embodiment, image data in RGB color space, which has been outputted by the pseudo color removing processor 21, is converted from RGB
15 color space to YUV color space by the RGB/YUV converter 12 to be subjected to JPEG compression. This YUV conversion is executed by the aforementioned equations (1) to (3).

20 According to the sixth embodiment, instead of the pseudo color removing processor 21, the median filters (median value filters) 17b and 17c execute filtering to U and V signals outputted by the RGB/YUV converter 12. Then, to perform JPEG compression, the LPF 14a and 14b
25 perform low pass filtering to color difference data to limit the band of the color difference signals. Then,

the thinning circuit 15 performs thinning into a predetermined format, e.g., from Y:U:V = 4:4:4 to Y:U:V = 4:2:2 or Y:U:V = 4:1:1, and compression is performed by the JPEG compression circuit 16.

5 For the isolated point removing filter, filtering called smoothing (Edge Preserving Smoothing) for preserving edges, which has been described in the fourth embodiment, may be employed besides the above-described median filter.

10 Furthermore, for the isolated point removing filter, smoothing (Maximum Homogeneity Smoothing) for preserving edges, which has been described in the fourth embodiment, may be employed.

Besides the above, filtering called hysteresis
15 smoothing may be employed. More specifically, a hysteresis characteristic is produced for a data value, and noise is absorbed by the hysteresis characteristic. Any of the aforementioned filters may be used as long as interpolation or smoothing is performed by using
20 outputs of peripheral pixels of an isolated point having a pixel value largely different from peripheral pixel values.

[Seventh Embodiment]

25 A characteristic feature of the seventh embodiment is described before explaining a specific

example of the seventh embodiment. To eliminate the above-described pseudo colors, it is ideal to employ three-plate camera where CCDs are provided for each of the R, G and B color components. With such structure, the size of a camera increases. In the seventh embodiment, an attention is directed to the fact that pseudo colors generated from red (R) to yellow (Y) and from blue (B) to cyan (C) have high frequencies. Thus, the characteristic feature of the seventh embodiment is to suppress generation of pseudo colors by reducing the gain of a color difference signal when the luminance signal has a high frequency component and the hue falls within a predetermined range.

Fig. 9 is a block diagram showing, mainly, a construction of an image processing unit of a digital camera according to the seventh embodiment of the present invention.

Light 1, incident upon the camera, passes through the lens 2, then the amount of the light is adjusted by the diaphragm 3, and the image sensing device 5 (hereinafter referred to as a CCD), e.g., CCD or CMOS, is exposed while a shutter (not shown) is open. Before the light 1 is incident upon the CCD 5, a frequency area (band) of a long wavelength is cut off by the IR filter 4 so that the CCD 5 does not detect light in the infrared region. The light incident upon the CCD 5 is

accumulated in the CCD 5 as an electric charge, and
outputted as an electric signal. The electric signal
is amplified by a predetermined gain by the CDS-AGC 6,
and converted to digital data by the A/D converter 7.

5 Image data converted to digital data in the foregoing
manner is transferred to the white balance circuit 8
where R, G and B gains are adjusted. Then, in the
color interpolator 9, the image data is generated in,
for instance, three color (R, G and B) planes as shown
10 in Fig 10. The image data expressed in the R, G and B
planes are then transferred to the masking processor 10
where adjustment is made for the hue of the R, G and B
colors. Then, the gamma converter 11 performs
necessary processing for displaying an image on a
15 display or the like. Further, compression processing
according to JPEG or the like is performed on the image
data since the data in the R, G and B color planes has
a large amount of data.

First, RGB/Y converter 22 converts RGB color
20 space to color space of Y color difference signal. The
conversion is executed by, for instance, above-
mentioned equations (1) to (3).

To detect high frequency components and hue, the
image data, expressed in the R, G and B planes by the
25 color interpolator 9, is subjected to calculation of a
luminance signal Y by the RGB/Y converter 22, using the

aforementioned equation (1). Next, to obtain a high frequency component of the obtained luminance signal Y, a spatial high pass filter (HPF) 23 executes spatial high pass filter computation as shown in Fig. 11. The
5 luminance signal Y, obtained by the RGB/Y converter 22, is transferred to a hue detection circuit 24 for detecting a hue, where color difference signals R-Y and B-Y are calculated and a hue is detected based on the calculated results. The detected hue data is outputted
10 to a pseudo color suppression circuit 13. Referring to Fig. 11, spatial high pass filter computation is executed by multiplying an input signal by a matrix 300, and subtracting the input signal from the multiplication result by a subtractor 301.

15 The pseudo color suppression circuit 13 suppresses pseudo colors by reducing gains of U and V, outputted by the RGB/Y converter 22, based on the high frequency component of the luminance signal Y obtained by the spatial high pass filter 23 and the hue data
20 obtained by the hue detection circuit 24.

The pseudo color suppression processing is described with reference to Figs. 12 and 13.

First, it is determined whether or not a color of the pixel of interest falls within a predetermined
25 range (area indicated by hatching in Fig. 13) in Y, R-Y, B-Y color space. If the color is determined to be in

the range where it is considered as a pseudo color, gains of the color difference signals U and V, having a predetermine value of 1 or larger as shown in Fig. 12, are reduced in accordance with a high frequency component value of the luminance signal outputted by the spatial high pass filter 23. By this, pseudo colors can be suppressed.

Pseudo color suppression processing performed in the above-described configuration is explained. A high frequency component, such as that having a vertical stripe pattern or a checker flag pattern described with reference to Figs. 19 to 22, is extracted by the spatial HPF 23. The aforementioned pseudo color generation is prevented by reducing gains of color difference signals U and V in the extracted high frequency area, which may cause pseudo colors described in Figs. 19 to 22 (for instance, predetermined areas of R and Y components in Fig. 19, predetermined areas of C and B components in Fig. 20, or predetermined areas of R and B components in Figs. 21 and 22, all of which correspond to the hatching portion in Fig. 13).

Next, the low pass filter (LPF) 14 execute low pass filtering in the horizontal or vertical direction. Then, the thinning circuit 15 performs thinning processing of the color difference signals, in accordance with a predetermined JPEG format, e.g., from

Y:U:V = 4:4:4 to Y:U:V = 4:2:2 or Y:U:V = 4:1:1. Then,
the JPEG compression circuit 16 performs JPEG
compression. By this, a compressed image having less
pseudo colors can be generated.

5 Note herein that instead of calculating the
luminance signal Y by the aforementioned equation (1),
the calculation may be executed with a simplified
luminance signal Y_e . For instance, aforementioned
equation (7), $Y_e = R + 2 \times G + B$, may be used.

10 Alternatively, a green (G) signal component may
be used as a luminance signal without calculating the
luminance signal.

Fig. 14 is a flowchart explaining pseudo color
removing processing according to the seventh embodiment
15 of the present invention.

Referring to Fig. 14, in step S1, R, G and B
signals of an image, upon which color interpolation
processing has been performed, are inputted and a
luminance signal Y is generated from the R, G and B
20 signals by the RGB/Y converter 22. In step S2, high
frequency components of the luminance signal Y are
extracted by the spatial high pass filter (HPF) 23. In
step S3, differences are respectively calculated
between each of R, B signals and the luminance signal Y
25 by the hue detection circuit 24, and color difference
signals R-Y and B-Y are generated. In step S4, a hue

signal is generated based on the color difference signals, and it is determined whether or not the hue signal falls within a color range that is considered as pseudo colors. If it is determined as a pseudo color
5 in step S5, the control proceeds to step S6 where gains of the color difference signals in the pseudo color portion are reduced in accordance with the amount of high frequency component of the pixel. By this, for instance, in the color space corresponding to the
10 hatching area in Fig. 13, pseudo color components generated by color interpolation can be suppressed. Then the process proceeds to step S7, isolated pixels of the image are removed.

As described above, the seventh embodiment
15 achieves an effect of preventing pseudo colors generation from red to yellow and from blue to cyan.

[Eighth Embodiment]

A characteristic feature of the eighth embodiment
20 is described before explaining a specific example of the eighth embodiment. To eliminate the above-described pseudo colors, it is ideal to employ three-plate camera where CCDs are provided for each of the R, G and B color components. With such structure, the
25 size of a camera increases. In the eighth embodiment, an attention is directed to the fact that pseudo colors

generated from red (R) to yellow (Y) and from blue (B) to cyan (C) have high frequencies. Thus, the characteristic feature of the eighth embodiment is to suppress generation of pseudo colors by removing an isolated point of a luminance signal, having a high frequency component and, if the hue falls within a predetermined range, reducing the gain of the color difference signal.

Fig. 15 is a block diagram showing, mainly, a construction of an image processing unit of a digital camera according to the eighth embodiment of the present invention.

The pseudo color suppression circuit 13 suppresses pseudo colors by reducing gains of U and V, outputted by the RGB/YUV converter 22, based on a high frequency component of the luminance signal Y obtained by the spatial high pass filter 23 and hue data obtained by the hue detection circuit 24. The pseudo color suppression processing is performed in the same manner as that of the above-described seventh embodiment.

Among the above-described pseudo colors, patterns of pseudo colors from red (R) to yellow (Y) and from blue (B) to cyan (C) can be determined as pseudo colors by detecting high frequency components of the luminance signal because the degree of luminance of pseudo colors

are different from others. However, pseudo colors generated around a character are often isolated, and the degree of luminance of the pseudo colors are not always different from the peripheral pixel luminance.

5 In view of the above, according to the eighth embodiment, the median filters 24a and 24b remove isolated points with respect to the color difference signals U and V and further perform pseudo color removal. Figs. 2A and 2B explain this processing.

10 Herein, elements having 3×3 pixel area including a pixel of interest are arranged in the ascending order, and the value of the pixel of interest is replaced with a median value of the arranged pixels. By this, a pixel, having a color of extremely different hue from

15 the hues of peripheral pixels, can be eliminated. Particularly, since the low pass filtering is not executed in the eighth embodiment, resolution does not decrease largely, thus does not influence peripheral pixels.

20 Pseudo color suppression processing performed in the above-described configuration is explained. A high frequency component, such as that having a vertical stripe pattern or a checker flag pattern described with reference to Figs. 19 to 22, is extracted by the

25 spatial HPF 23. The aforementioned pseudo color generation is prevented by reducing gains of color

difference signals U and V in the extracted high frequency area, which may cause the pseudo colors described in Figs. 19 to 22 (for instance, predetermined areas of R and Y components in Fig. 19, 5 predetermined areas of C and B components in Fig. 20, or predetermined areas of R and B components in Figs. 21 and 22, all of which correspond to the hatching portion in Fig. 13). After pseudo colors are suppressed in the foregoing manner, the median filters 10 24a and 24b execute above-described filtering, thereby removing isolated pixels.

Next, the low pass filter (LPF) 14a and 14b execute low pass filtering in the horizontal or vertical direction. Then, the thinning circuit 15 15 performs thinning processing of the color difference signals, in accordance with a predetermined JPEG format, e.g., from Y:U:V = 4:4:4 to Y:U:V = 4:2:2 or Y:U:V = 4:1:1. Then, the JPEG compression circuit 16 performs JPEG compression. By this, a compressed image having 20 less pseudo colors can be generated.

Note that, to calculate the luminance signal Y, the aforementioned equation (7) may be used.

Alternatively, a green (G) signal component may be used as a luminance signal without calculating the 25 luminance signal.

Since the pseudo color removal processing

according to the eighth embodiment is performed in the same manner as that explained in the flowchart in Fig. 14, detailed description will be omitted herein.

5 [Ninth Embodiment]

In the foregoing seventh and eighth embodiments, means for detecting pseudo colors is provided after the color interpolator 9 and pseudo color detection is performed using signals in the R, G and B planes. The
10 reason is that, since processing such as masking processing, γ conversion and so forth that may cause changes in hue are performed after the color interpolator 9, the hue range of the detected pseudo colors may change. Because of this reason, the
15 luminance signal Y is calculated to obtain color difference signals R-Y and B-Y. However, the pseudo color detection means does not have to be provided in this position. For instance, in order to perform JPEG compression, RGB color space must be converted to a
20 color space of luminance or color difference. Therefore, pseudo colors can be detected from these signals. The ninth embodiment relates to such case. Note that, as mentioned above, there is a possibility that the hue range of pseudo colors changes depending
25 on images.

Fig. 16 is a block diagram showing a construction

of an image processing unit of a digital camera according to the ninth embodiment of the present invention. For the components that are common to the construction shown in Fig. 9, the same reference
5 numerals are assigned.

Light 1, incident upon the camera, passes through the lens 2, then the amount of the light is adjusted by the diaphragm 3, and the CCD 5 is exposed while a shutter (not shown) is open. Before the light 1 is
10 incident upon the CCD 5, a frequency area of a long wavelength is cut off by the IR filter 4 so that the CCD 5 does not detect light in the infrared region. The light incident upon the CCD 5 is accumulated in the CCD 5 as an electric charge, and outputted as an
15 electric signal. The electric signal is amplified by a predetermined gain by the CDS-AGC 6, and converted to digital data by the A/D converter 7. Image data converted to digital data in the foregoing manner is transferred to the white balance circuit 8 where R, G
20 and B gains are adjusted. Then, in the color interpolator 9, the image data is generated in, for instance, three color (R, G and B) planes as shown in Fig. 2. The image data expressed in the R, G and B planes are then transferred to the masking processor 10
25 where adjustment is made for the hue of the R, G and B colors. Then, the gamma converter 11 performs

necessary processing for displaying an image on a display or the like. Then, RGB/YUV converter 12 converts the image data from RGB color space to color space of Y color difference signal.

5 Among the converted signals, luminance signal Y is transmitted to the spatial high pass filter (HPF) 25 for detecting high frequency components of the signal by the filtering shown in Fig. 11. Then, a hue
10 detection circuit 26 determines whether or not a pixel of interest falls within the hue range of pseudo colors. Herein, instead of the above-described color space R-Y and B-Y shown in Fig. 13, U and V outputted by the RGB/YUV converter 12 are used as shown in Fig. 17.

 As similar to the seventh and eighth embodiments,
15 if it is determined that a color of the pixel of interest falls within the hue range of pseudo colors, the pseudo color suppression circuit 13 reduces gains of the color difference signals U and V, having a value of 1 or larger as shown in Fig. 12, in accordance with
20 an output value of the spatial HPF 25.

 In this case, for instance, it may be necessary to change, for instance, the hue range depending on the white balance. For instance, when the gain of red is increased, the hue range is shifted towards red, or a
25 hue angle is widened.

 Next, the LPF 14a and 14b execute low pass

filtering in the horizontal or vertical direction. Then, the thinning circuit 15 performs thinning processing of the color difference signals, in accordance with a predetermined JPEG format, e.g., from Y:U:V = 4:4:4 to Y:U:V = 4:2:2 or Y:U:V = 4:1:1. Then, the JPEG compression circuit 16 performs JPEG compression.

By this, a compressed image having less pseudo colors can be generated.

[Tenth Embodiment]

In the foregoing seventh and eighth embodiments, means for detecting pseudo colors is provided after the color interpolator 9 and pseudo color detection is performed using signals in the R, G and B planes. The reason is that, since processing such as masking processing, γ conversion and so forth that may cause changes in hue are performed after the color interpolator 9, the hue range of the detected pseudo colors may change. Because of this reason, the luminance signal Y is calculated to obtain color difference signals R-Y and B-Y. However, the pseudo color detection means does not have to be provided in this position. For instance, in order to perform JPEG compression, RGB color space must be converted to a color space of luminance and color difference.

Therefore, pseudo colors can be detected from these signals. With reference to the foregoing eighth embodiment (Fig. 15), in the median filters 24a and 24b where pseudo color suppression is performed, delay is
5 generated between the luminance signal Y and color difference signals U and V. Because of this, the luminance signal must also be delayed. The tenth embodiment makes use of this delay.

Fig. 18 is a block diagram showing a construction
10 of an image processing unit of a digital camera according to the tenth embodiment of the present invention. For the components that are common to the construction shown in Fig. 15, the same reference numerals are assigned.

15 Light 1, incident upon the camera, passes through the lens 2, then the amount of the light is adjusted by the diaphragm 3, and the CCD 5 is exposed while a shutter (not shown) is open. Before the light 1 is incident upon the CCD 5, a frequency area of a long
20 wavelength is cut off by the IR filter 4 so that the CCD 5 does not detect light in the infrared region. The light incident upon the CCD 5 is accumulated in the CCD 5 as an electric charge, and outputted as an electric signal. The electric signal is amplified by a
25 predetermined gain by the CDS-AGC 6, and converted to digital data by the A/D converter 7. Image data

converted to digital data in the foregoing manner is transferred to the white balance circuit 8 where R, G and B gains are adjusted. Then, in the color interpolator 9, the image data is generated in, for instance, three color (R, G and B) planes as shown in Fig. 2. The image data expressed in the R, G and B planes are then transferred to the masking processor 10 where adjustment is made for the hue of the R, G and B colors. Then, the gamma converter 11 performs necessary processing for displaying an image on a display or the like. Then, RGB/YUV converter 12 converts the image data from RGB color space to color space of Y color difference signal.

Among the converted signals, luminance signal Y is transmitted to the spatial high pass filter (HPF) 15 for detecting high frequency components of the luminance signal by the filtering shown in Fig. 11. Meanwhile, color difference signals U and V are transmitted to the median filters 24a and 24b for executing the above-described median filtering shown in Figs. 2A and 2B. By virtue of this, while high frequency components of the luminance signal Y are detected, median filtering is executed to the color difference signals. Therefore, it is possible to reduce wasteful use of a memory caused by delay of one of the signals.

Next, the hue detection circuit 26 determines whether or not a pixel of interest falls within the hue range of pseudo colors. Herein, instead of the above-described color space R-Y and B-Y shown in Fig. 13, U and V outputted by the RGB/YUV converter 12 are used as shown in Fig. 17.

As similar to the eighth embodiment, if it is determined that a color of the pixel of interest falls within the hue range of pseudo colors, the pseudo color suppression circuit 13 reduces gains of the color difference signals U and V, having a value of 1 or larger as shown in Fig. 12, in accordance with an output value of the spatial HPF 25.

In this case, for instance, it may be necessary to change, for instance, the hue range depending on the white balance. For instance, when the gain of red is increased, the hue range is shifted to the red, or a hue angle is widened.

Next, the LPF 14a and 14b execute low pass filtering in the horizontal or vertical direction. Then, the thinning circuit 15 performs thinning processing of the color difference signals, in accordance with a predetermined JPEG format, e.g., from $Y:U:V = 4:4:4$ to $Y:U:V = 4:2:2$ or $Y:U:V = 4:1:1$. Then, the JPEG compression circuit 16 performs JPEG compression.

By this, a compressed image having less pseudo colors can be generated.

The present invention can be applied to a system constituted by a plurality of devices (e.g., host computer, interface, reader, printer) or to an apparatus comprising a single device (e.g., copying machine, facsimile machine).

Further, the object of the present invention can also be achieved by providing a storage medium storing program codes for performing the aforesaid processes to a computer system or apparatus (e.g., a personal computer), reading the program codes, by a computer (CPU or MPU) of the system or apparatus, from the storage medium, then executing the program.

In this case, the program codes read from the storage medium realize the functions according to the embodiments, and the storage medium storing the program codes constitutes the invention.

Further, the storage medium, such as a floppy disk, a hard disk, an optical disk, a magneto-optical disk, CD-ROM, CD-R, a magnetic tape, a non-volatile type memory card, and ROM can be used for providing the program codes.

Furthermore, besides aforesaid functions according to the above embodiments are realized by executing the program codes which are read by a

computer, the present invention includes a case where
an OS (operating system) or the like working on the
computer performs a part or the entire processes in
accordance with designations of the program codes and
5 realizes functions according to the above embodiments.

Furthermore, the present invention also includes
a case where, after the program codes read from the
storage medium are written in a function expansion card
which is inserted into the computer or in a memory
10 provided in a function expansion unit which is
connected to the computer, CPU or the like contained in
the function expansion card or unit performs a part or
the entire process in accordance with designations of
the program codes and realizes functions of the above
15 embodiments.

As has been set forth above, according to the
above-described embodiments, RGB color space is
converted to YUV or Y, R-Y, B-Y or G, R-G, B-G color
space, and isolated point removing filtering (e.g.,
20 median filter or the like) is executed respectively to
color difference signals in UV, or R-Y, B-Y or R-G, B-G
color space, thereby enabling reduction of pseudo
colors generated by color interpolation.

Furthermore, according to the above-describe
25 embodiments, even if an optical low pass filter is not
provided before the image sensing device, such as CCD

or the like, pseudo color components can be reduced by converting RGB color space to $L^*a^*b^*$ or YUV color space, then performing filtering to color difference signals such as a^* and b^* signals or U and V signals with the isolated point removing filter, and then performing compression according to JPEG or the like. Accordingly, an image, having less block distortion and reduced pseudo color components, can be obtained.

Furthermore, according to the above-described
10 embodiments, pseudo colors generated by color interpolation can be suppressed by detecting high frequency components of a luminance signal and pseudo colors generated from red to yellow and from blue to cyan in the hue, and then reducing gains of color
15 difference signals U and V.

Still further, according to the above-described
embodiments, pseudo colors generated by color interpolation can be suppressed by detecting high frequency components of a luminance signal and pseudo
20 colors generated from red to yellow and from blue to cyan in the hue, then reducing gains of color difference signals U and V, and further eliminating isolated pixels.

Still further, according to the above-described
25 embodiments, pseudo colors generated by color interpolation can be suppressed by executing median

filtering to color difference signals in the color
space of luminance and color difference signals, then
detecting high frequency components of a luminance
signal and pseudo colors generated from red to yellow
5 and from blue to cyan in color difference signals, and
reducing gains of color difference signals U and V.

Still further, according to the above-described
embodiments, by executing median filtering to color
difference signals while detecting high frequency
10 components of a luminance signal, it is possible to
eliminate a processing circuit necessary to match
delayed timing of the luminance signal and color
difference signals.

The present invention is not limited to the above
15 embodiments and various changes and modifications can
be made within the spirit and scope of the present
invention. Therefore, to apprise the public of the
scope of the present invention, the following claims
are made.

WHAT IS CLAIMED IS:

1. An image sensing apparatus comprising:
an image sensing device;
5 focusing means for focusing into an image on said
image sensing device;

A/D conversion means for converting an image
signal outputted by said image sensing device into a
digital signal;

10 color interpolation means for performing color
interpolation on the digital signal converted by said
A/D conversion means and generating image data on a
plurality of color planes;

color space conversion means for converting a
15 color space of the plurality of color planes to a color
space of another colorimetric system; and

pseudo color removing means for reducing a color
component, generated by said color interpolation means,
by controlling a color difference signal converted by
20 said color space conversion means.

2. The image sensing apparatus according to
claim 1, wherein said pseudo color removing means
includes an isolated point removing filter which
25 replaces a value of a pixel of interest with a
substantial median pixel value of peripheral pixels of

the pixel of interest.

3. The image sensing apparatus according to claim 2, wherein said isolated point removing filter
5 includes a median value filter or median filter.

4. The image sensing apparatus according to claim 1, wherein said color interpolation means
generates image data in R, G and B planes.
10

5. The image sensing apparatus according to claim 1, wherein said color space conversion means
converts RGB color space to YUV color space.
15

6. The image sensing apparatus according to claim 1, wherein said color space conversion means
converts RGB color space to Y, R-Y, B-Y color space.
20

7. The image sensing apparatus according to claim 1, wherein said color space conversion means
converts RGB color space to G, R-G, B-G color space.
25

8. The image sensing apparatus according to claim 1, wherein said focusing means includes an
infrared ray filter, or an infrared ray filter and
optical low pass filter.

9. An image sensing apparatus comprising:
an image sensing device;
focusing means for focusing into an image on said
5 image sensing device;

A/D conversion means for converting an image
signal outputted by said image sensing device into a
digital signal;

color interpolation means for performing color
10 interpolation on the digital signal converted by said
A/D conversion means and generating image data on a
plurality of color planes;

pseudo color removing means for reducing a color
component included in image data, on which color
15 interpolation is performed by said color interpolation
means;

color space conversion means for converting a
color space of the plurality of color planes, where the
color component is reduced by said pseudo color
20 removing means, to a color space of another
colorimetric system; and

compression means for compressing image data
where color space is converted by said color space
conversion means.

25

10. The image sensing apparatus according to

claim 9, wherein said pseudo color removing means comprises:

first color space conversion means for converting a color space of the plurality of color planes to a color space of another colorimetric system;

isolated point removing means for reducing an isolated pseudo color component by controlling signals except a luminance component signal of the colorimetric system converted by said first color space conversion means; and

second color space conversion means for converting the color space, converted by said first color space conversion means, to an original color space.

15

11. The image sensing apparatus according to claim 10, wherein said isolated point removing means includes an isolated point removing filter which replaces a value of a pixel of interest with a substantial median pixel value of peripheral pixels of the pixel of interest.

12. The image sensing apparatus according to claim 11, wherein said isolated point removing filter includes a median value filter or median filter.

25

13. The image sensing apparatus according to claim 10, wherein said color interpolation means generates image data in R, G and B planes.

5 14. The image sensing apparatus according to claim 11, wherein said first color space conversion means converts RGB color space to $L^*a^*b^*$ color space, and said isolated point removing means causes the isolated point removing filter to filter a frequency
10 range of a^* and b^* signals.

15 15. The image sensing apparatus according to claim 10, wherein said color space conversion means converts RGB color space to YUV color space.

16. An image sensing apparatus comprising:
an image sensing device;
focusing means for focusing into an image on said
image sensing device;

20 A/D conversion means for converting an image signal outputted by said image sensing device into a digital signal;

color interpolation means for performing color interpolation on the digital signal converted by said
25 A/D conversion means and generating image data on a plurality of color planes;

separation means for separating the image data in the plurality of color planes into luminance data and color difference data;

5 extraction means for extracting a high frequency component from the luminance data separated by said separation means; and

pseudo color removing means for reducing a color component generated by said color interpolation means, in accordance with the high frequency component of the
10 luminance data extracted by said extraction means and hue data obtained from the color difference data.

17. The image sensing apparatus according to claim 16, wherein said pseudo color removing means
15 comprises:

determination means for determining whether or not the high frequency component of the luminance data and the hue data fall within a color range of the pseudo color; and

20 means for reducing a value of the color difference data, determined to be within the color range by said determination means.

18. An image sensing apparatus comprising:
25 an image sensing device;
focusing means for focusing into an image on said

image sensing device;

A/D conversion means for converting an image signal outputted by said image sensing device into a digital signal;

5 color interpolation means for performing color interpolation on the digital signal converted by said A/D conversion means and generating image data on a plurality of color planes;

10 color space conversion means for converting a color space of the plurality of color planes to a color space of another colorimetric system;

separation means for separating image data in the color space of another colorimetric system into luminance data and hue data;

15 extraction means for extracting a high frequency component from the luminance data separated by said separation means; and

pseudo color removing means for reducing a color component generated by said color interpolation means, 20 in accordance with the high frequency component of the luminance data extracted by said extraction means and the hue data.

19. The image sensing apparatus according to 25 claim 18, wherein said pseudo color removing means comprises:

determination means for determining whether or not the high frequency component of the luminance data and the hue data fall within a color range of the pseudo color; and

- 5 means for reducing a value of the color difference data, determined to be within the color range by said determination means.

20. The image sensing apparatus according to
10 claim 18, wherein said color space conversion means converts the color space to YUV, or Y, R-Y, B-Y, or G, R-G, B-G color space.

21. The image sensing apparatus according to
15 claim 18, further comprising a low pass filter for removing a high frequency component from a color signal, from which a pseudo color is removed by said pseudo color removing means.

22. The image sensing apparatus according to
20 claim 18, wherein the color range of a pseudo color includes a color area from red to yellow, and a color area from blue to cyan.

23. The image sensing apparatus according to
25 claim 18, further comprising isolated point removing

means for removing an isolated pixel from a hue signal,
from which the pseudo color is removed by said pseudo
color removing means.

5 24. The image sensing apparatus according to
claim 23, wherein said isolated point removing means
includes a median filter.

25. An image sensing apparatus comprising:
10 an image sensing device;
 focusing means for focusing into an image on said
image sensing device;

 A/D conversion means for converting an image
signal outputted by said image sensing device into a
15 digital signal;

 color interpolation means for performing color
interpolation on the digital signal converted by said
A/D conversion means and generating image data on a
plurality of color planes;

20 color space conversion means for converting a
color space of the plurality of color planes to a color
space of another colorimetric system;

 separation means for separating image data in the
color space of another colorimetric system into
25 luminance data and hue data;

 extraction means for extracting a high frequency

component from the luminance data separated by said separation means;

isolated point removing means for removing an isolated pixel based on the hue data separated by said separation means; and

pseudo color removing means for reducing a color component generated by said color interpolation means, in accordance with the high frequency component of the luminance data extracted by said extraction means and the hue data from which an isolated pixel is removed by said isolated point removing means.

26. The image sensing apparatus according to claim 25, wherein said pseudo color removing means comprises:

determination means for determining whether or not the high frequency component of the luminance data and the hue data fall within a color range of the pseudo color component; and means for reducing a value of the color difference data, determined to be within the color range by said determination means.

27. The image sensing apparatus according to claim 25, wherein said color space conversion means converts the color space to YUV, or Y, R-Y, B-Y, or G,

R-G, B-G color space.

28. The image sensing apparatus according to claim 25, further comprising a low pass filter for removing a high frequency component from a color signal, from which a pseudo color is removed by said pseudo color removing means.

29. The image sensing apparatus according to claim 25, wherein the color range of the pseudo color includes a color area from red to yellow, and a color area from blue to cyan.

30. An image processing method for an image sensing apparatus which includes an image sensing device and generates an image signal corresponding to an image formed on the image sensing device, comprising:

an A/D conversion step of converting an image signal outputted by the image sensing device into a digital signal;

a color interpolation step of performing color interpolation on the digital signal converted in said A/D conversion step and generating image data on a plurality of color planes;

a color space conversion step of converting a

color space of the plurality of color planes to a color space of another colorimetric system; and

a pseudo color removing step of reducing a color component, generated in said color interpolation step,
5 by controlling a color difference signal converted in said color space conversion step.

31. The image processing method according to claim 30, wherein in said pseudo color removing step, a
10 value of a pixel of interest is replaced with a substantial median pixel value of peripheral pixels of the pixel of interest.

32. The image processing method according to claim 30, wherein in said pseudo color removing step,
15 filtering is performed by a median value filter or median filter.

33. The image processing method according to claim 30, wherein in said color interpolation step,
20 image data is generated in R, G and B planes.

34. The image processing method according to claim 30, wherein in said color space conversion step,
25 RGB color space is converted to YUV color space.

35. The image processing method according to claim 30, wherein in said color space conversion step, RGB color space is converted to Y, R-Y, B-Y color space.

5 36. The image processing method according to claim 30, wherein in said color space conversion step, RGB color space is converted to G, R-G, B-G color space.

37. An image processing method for an image
10 sensing apparatus which includes an image sensing device and generates an image signal corresponding to an image formed on the image sensing device, comprising:

an A/D conversion step of converting an image
15 signal outputted by the image sensing device into a digital signal;

a color interpolation step of performing color interpolation on the digital signal converted in said A/D conversion step and generating image data on a
20 plurality of color planes;

a pseudo color removing step of reducing a color component included in image data, on which color interpolation is performed in said color interpolation step;

25 a color space conversion step of converting a color space of the plurality of color planes, where a

pseudo color component is reduced in said pseudo color removing step, to a color space of another colorimetric system; and

a compression step of compressing image data
5 where color space is converted in said color space conversion step.

38. The image processing method according to claim 37, wherein in said pseudo color removing step, a
10 value of a pixel of interest is replaced with a substantial median pixel value of peripheral pixels of the pixel of interest.

39. The image processing method according to
15 claim 37, wherein in said pseudo color removing step, filtering is performed by a median value filter or median filter.

40. The image processing method according to
20 claim 37, wherein in said color interpolation step, image data is generated in R, G and B planes.

41. The image processing method according to claim 37, wherein in said color space conversion step,
25 RGB color space is converted to $L^*a^*b^*$ color space, and filtering is performed to a^* and b^* signals in said

pseudo color removing step.

42. The image processing method according to claim 37, further comprising a conversion step of
5 converting the signal, processed in said pseudo color removing step, into YUV color space.

43. The image processing method according to claim 37, wherein in said compression step, image data
10 converted to YUV color space is compressed.

44. An image processing method for an image sensing apparatus which includes an image sensing device and generates an image signal corresponding to
15 an image formed on the image sensing device, comprising:

an A/D conversion step of converting an image signal outputted by the image sensing device into a digital signal;

20 a color interpolation step of performing color interpolation on the digital signal converted in said A/D conversion step and generating image data on a plurality of color planes;

a separation step of separating the image data in
25 the plurality of color planes into luminance data and color difference data;

an extraction step of extracting a high frequency component from the luminance data separated in said separation step; and

5 a pseudo color removing step of reducing a color component generated in said color interpolation step, in accordance with the high frequency component of the luminance data extracted in said extraction step and hue data obtained from the color difference data.

10 45. The image processing method according to claim 44, wherein said pseudo color removing step comprises:

15 a determination step of determining whether or not the high frequency component of the luminance data and the hue data fall within a color range of the pseudo color; and

a step of reducing a value of the color difference data, determined to be within the color range in said determination step.

20

46. The image processing method according to claim 44, further comprising a step of removing a high frequency component from a color signal, from which the pseudo color is removed in said pseudo color removing
25 step.

47. The image processing method according to claim 44, wherein the color range of a pseudo color includes a color area from red to yellow, and a color area from blue to cyan.

5

48. An image processing method for an image sensing apparatus which includes an image sensing device and generates an image signal corresponding to an image formed on the image sensing device,

10 comprising:

an A/D conversion step of converting an image signal outputted by the image sensing device into a digital signal;

15 a color interpolation step of performing color interpolation on the digital signal converted in said A/D conversion step and generating image data on a plurality of color planes;

20 a color space conversion step of converting a color space of the plurality of color planes to a color space of another colorimetric system;

a separation step of separating image data in the color space of another colorimetric system into luminance data and hue data;

25 an extraction step of extracting a high frequency component from the luminance data separated in said separation step; and

a pseudo color removing step of reducing a color component generated in said color interpolation step, in accordance with the high frequency component of the luminance data extracted in said extraction step and
5 the hue data.

49. The image processing method according to claim 48, wherein said pseudo color removing step comprises:

10 a determination step of determining whether or not the high frequency component of the luminance data and the hue data fall within a color range of the pseudo color; and

15 a step of reducing a value of the color difference data, determined to be within the color range by said determination step.

50. The image processing method according to claim 48, wherein in said color space conversion step,
20 the color space is converted to YUV, or Y, R-Y, B-Y, or G, R-G, B-G color space.

51. The image processing method according to claim 48, further comprising a step of removing a high
25 frequency component from a color signal, from which the pseudo color is removed in said pseudo color removing

step.

52. The image processing step according to
claim 48, wherein the color range of a pseudo color
5 component includes a color area from red to yellow, and
a color area from blue to cyan.

53. An image processing method for an image
sensing apparatus which includes an image sensing
10 device and generates an image signal corresponding to
an image formed on the image sensing device,
comprising:

an A/D conversion step of converting an image
signal outputted by the image sensing device into a
15 digital signal;

a color interpolation step of performing color
interpolation on the digital signal converted in said
A/D conversion step and generating image data on a
plurality of color planes;

20 a separation step of separating image data in the
plurality of color planes into luminance data and color
difference data;

an extraction step of extracting a high frequency
component from the luminance data separated in said
25 separation step;

a pseudo color removing step of reducing a color

component generated in said color interpolation step,
in accordance with the high frequency component of the
luminance data extracted in said extraction step and
the hue data obtained from the color difference data;

5 and

an isolated point removing step of removing an
isolated pixel from the hue data, from which a pseudo
color component is removed in said pseudo color
removing step.

10

54. The image processing method according to
claim 53, wherein said pseudo color removing step
comprises:

a determination step of determining whether or
15 not the high frequency component of the luminance data
and the hue data fall within a color range of a pseudo
color component; and

a step of reducing a value of the color
difference data, determined to be within the color
20 range in said determination step.

55. The image processing method according to
claim 53, further comprising a step of removing a high
frequency component from a color signal, from which the
25 pseudo color is removed in said pseudo color removing
step.

56. The image processing method according to
claim 53, wherein the color range of the pseudo color
component includes a color area from red to yellow, and
5 a color area from blue to cyan.

57. An image processing method for an image
sensing apparatus which includes an image sensing
device and generates an image signal corresponding to
10 an image formed on the image sensing device,
comprising:

an A/D conversion step of converting an image
signal outputted by the image sensing device into a
digital signal;

15 a color interpolation step of performing color
interpolation on the digital signal converted in said
A/D conversion step and generating image data on a
plurality of color planes;

a color space conversion step of converting a
20 color space of the plurality of color planes to a color
space of another colorimetric system;

a separation step of separating image data in the
color space of another colorimetric system into
luminance data and hue data;

25 an isolating point removing step of removing an
isolated pixel based on the hue separated in said

separation step;

an extraction step of extracting a high frequency component from the luminance data separated in said separation step; and

- 5 a pseudo color removing step of reducing a color component generated in said color interpolation step, in accordance with the high frequency component of the luminance data extracted in said extraction step and the hue data from which an isolated pixel is removed in
10 said isolated point removing step.

58. The image processing method according to claim 57, wherein said pseudo color removing step comprises:

- 15 a determination step of determining whether or not the high frequency component of the luminance data and the hue data fall within a color range of the pseudo color; and

- a step of reducing a value of the color
20 difference data, determined to be within the color range in said determination step.

59. The image processing method according to claim 57, wherein in said color space conversion step,
25 the color space is converted to YUV, or Y, R-Y, B-Y, or G, R-G, B-G color space.

60. The image processing method according to claim 57, further comprising a step of removing a high frequency component from a color signal, from which the pseudo color is removed in said pseudo color removing step.

61. The image processing method according to claim 57, wherein the color range of the pseudo color component includes a color area from red to yellow, and a color area from blue to cyan.

ABSTRACT OF THE DISCLOSURE

An image sensing apparatus comprising: a CCD,
optical system for forming an image on the CCD; A/D
5 converter for converting an image signal outputted by
the CCD to a digital signal; color interpolator for
performing color interpolation on the digital signal
converted by the A/D converter and generating image
data on R, G and B color planes; color space converter
10 for converting RGB color space to YUV colorimetric
system; and median filter for reducing pseudo color
components, generated by the color interpolator, by
controlling color difference signals U and V. By
cutting high frequency components of the signal,
15 filtered by the median filter, then thinning out YUV
signals and performing JPEG compression, pseudo color
components generated by color interpolation can be
reduced.

FIG. 1

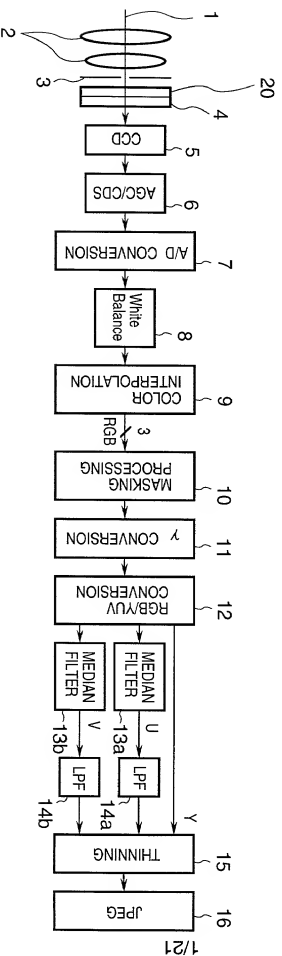


FIG. 2A

a^{*11} 8	a^{*12} 10	a^{*13} 12
a^{*21} 10	a^{*22} 20	a^{*23} 11
a^{*31} 9	a^{*32} 11	a^{*33} 10

 $a^{*22}=20$

↓ REPLACE

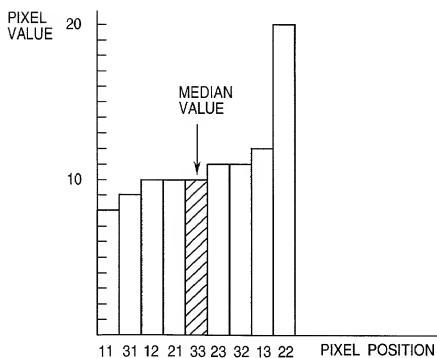
 $a^{*22}=10$ (MEDIAN VALUE)**FIG. 2B**

FIG. 3

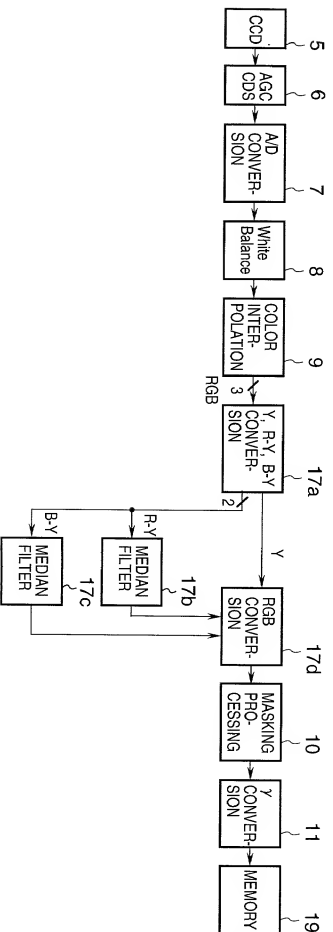


FIG. 4

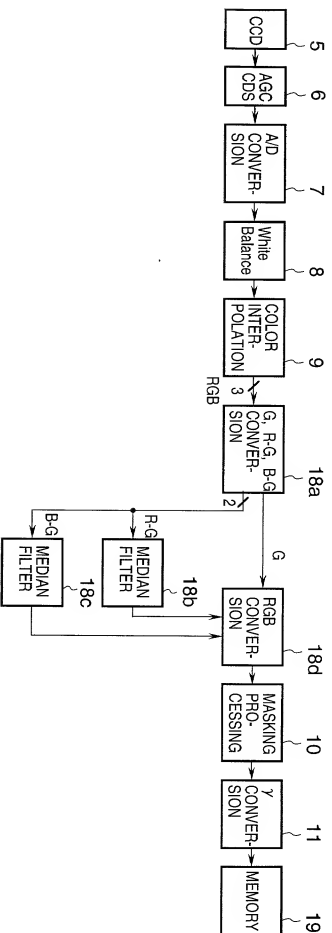


FIG. 5

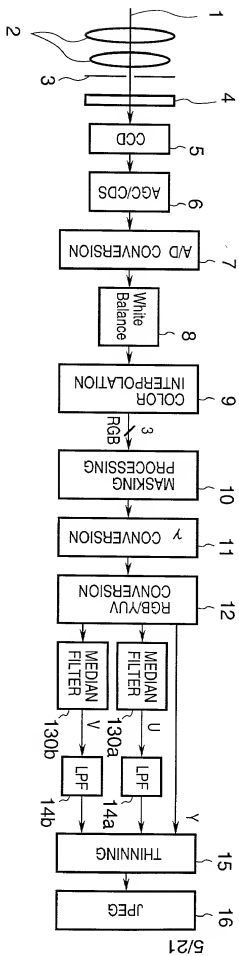


FIG. 6

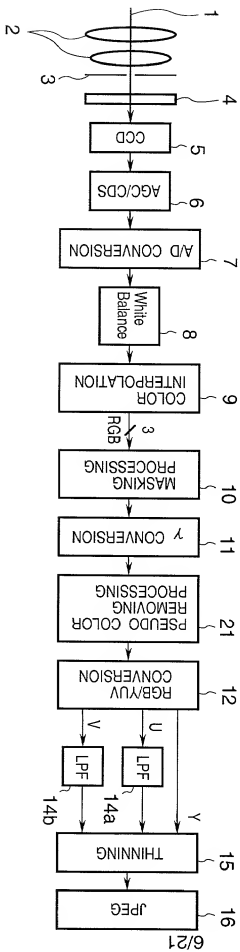


FIG. 7

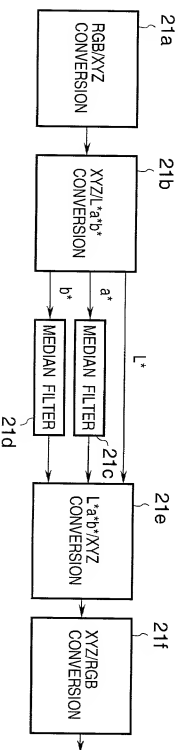


FIG. 8

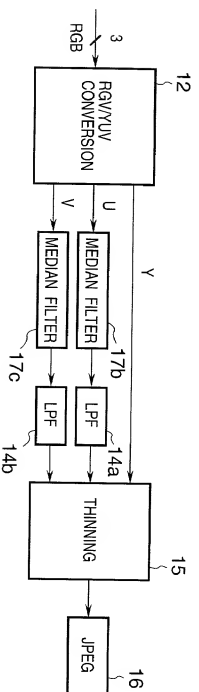


FIG. 9

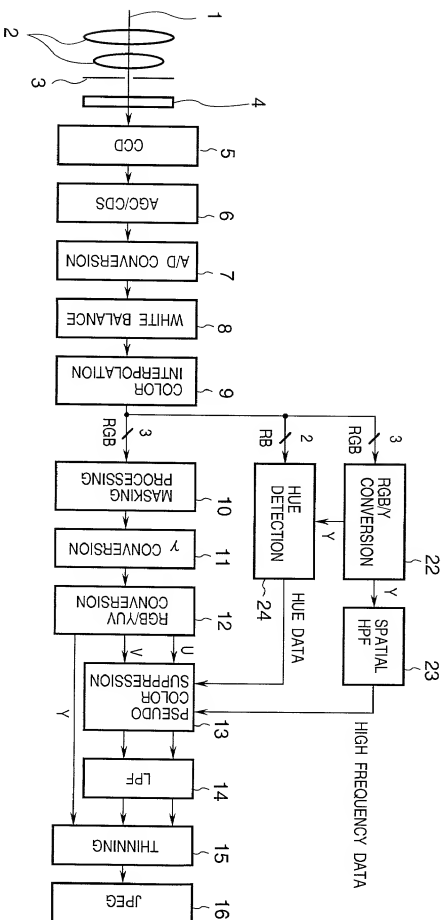


FIG. 10

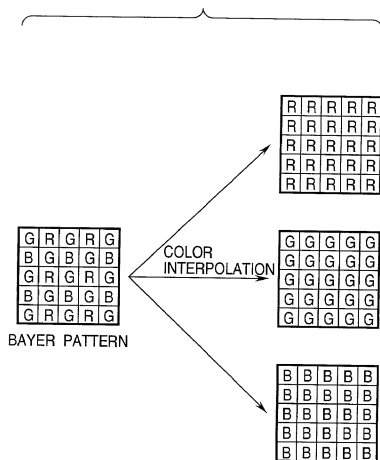


FIG. 11

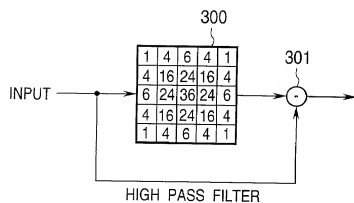


FIG. 12

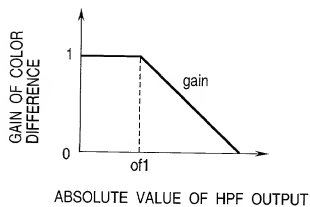


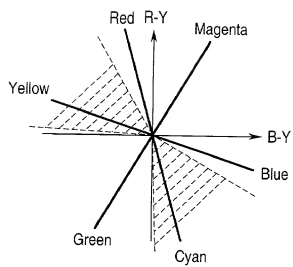
FIG. 13

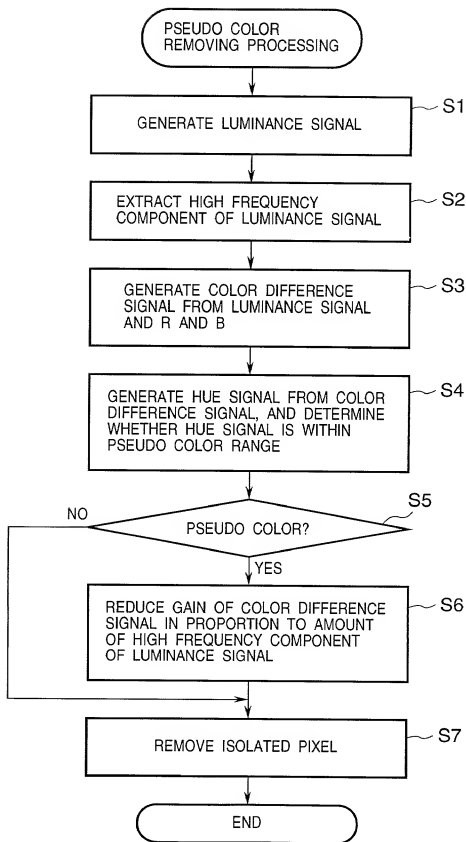
FIG. 14

FIG. 15

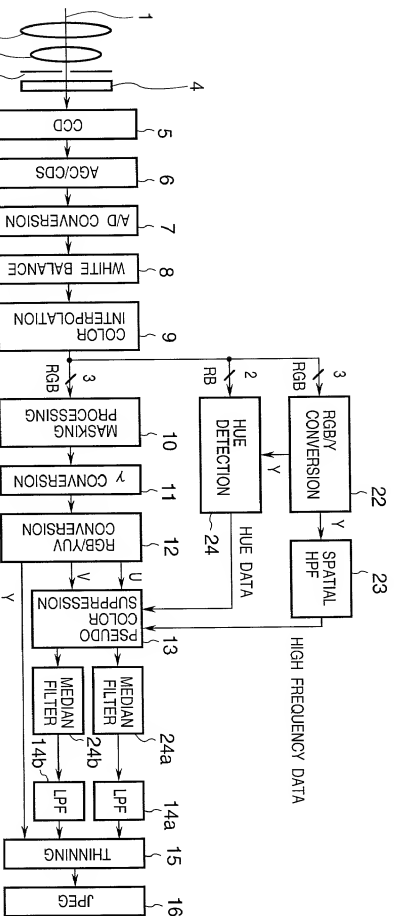


FIG. 16

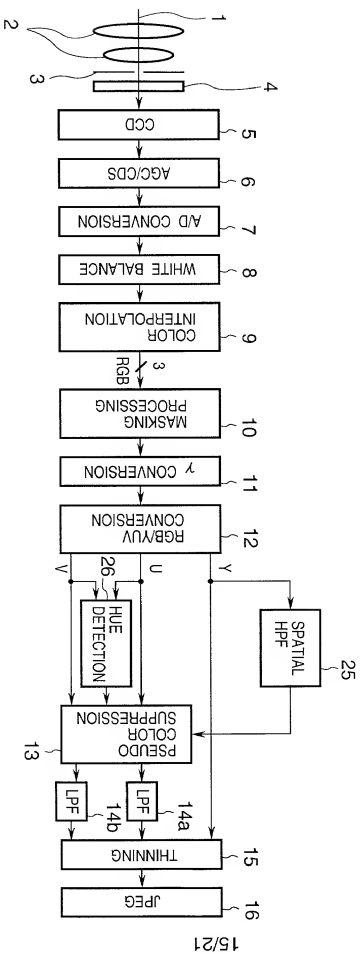


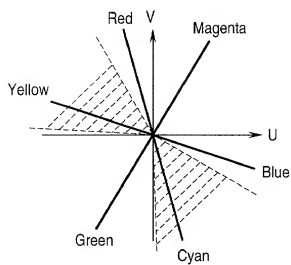
FIG. 17

FIG. 18

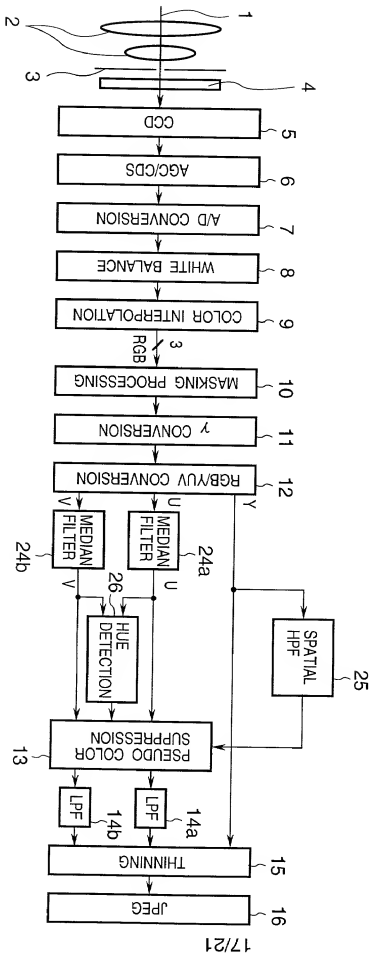


FIG. 19

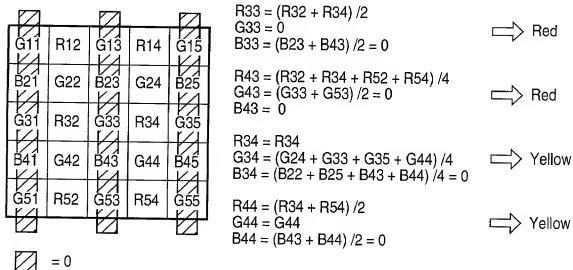










FIG. 20

G11		G13		G15
B21	G22	B23	G24	B25
G31		G33		G35
B41		B43		B45
G51		G53		G55

 = 0

$$R33 = (R32 + R34) / 2 = 0$$

$$G33 = G33$$

$$B33 = (B23 + B43) / 2$$

⇒ Cyan

$$R43 = (R32 + R34 + R52 + R54) / 4 = 0$$

$$G43 = (G33 + G53) / 2$$

$$B43 = B43$$

⇒ Cyan

$$R34 = 0$$

$$G34 = (G24 + G44) / 2 = 0$$

$$B34 = (B23 + B25 + B43 + B45) / 4$$

⇒ Blue

$$R44 = (R34 + R54) / 2 = 0$$

$$G44 = 0$$

$$B44 = (B43 + B45) / 2$$

⇒ Blue

FIG. 21


$\overline{G11}$	R12	$\overline{G13}$	R14	$\overline{G15}$
B21	$\overline{G22}$	B23	$\overline{G24}$	B25
$\overline{G31}$	R32	$\overline{G33}$	R34	$\overline{G35}$
B41	$\overline{G42}$	B43	$\overline{G44}$	B45
$\overline{G51}$	R52	$\overline{G53}$	R54	$\overline{G55}$

 = 0

$$R33 = (R32 + R34) / 2 = 0$$

$$G33 = 0$$


$$B33 = (B23 + B43) / 2$$

 Magenta

$$R43 = (R32 + R34 + R52 + R54) / 4$$

$$G43 = (G33 + G43 + G44 + G53) = 0$$


$$B43 = B43$$

 Magenta

$$R34 = R34$$

$$G34 = (G24 + G33 + G35 + G44) / 4 = 0$$

$$B34 = (B23 + B25 + B43 + B44) / 4$$

 Magenta

$$R44 = (R34 + R54)$$

$$G44 = G44$$

$$B44 = (B43 + B44) / 2$$


 Magenta

FIG. 22

G11	$\overline{R12}$	G13	$\overline{R14}$	G15
$\overline{B21}$	G22	$\overline{B23}$	G24	$\overline{B25}$
G31	$\overline{R32}$	G33	$\overline{R34}$	G35
$\overline{B41}$	G42	$\overline{B43}$	G44	$\overline{B45}$
G51	$\overline{R52}$	G53	$\overline{R54}$	G55

 = 0

$$R33 = (R32 + R34) / 2 = 0$$

$$G33 = G33$$

$$B33 = (B23 + B43) / 2 = 0$$

 Green

$$R43 = (R32 + R34 + R52 + R54) / 4 = 0$$

$$G43 = (G33 + G42 + G44 + G53) / 4$$

$$B43 = 0$$

 Green

$$R34 = 0$$

$$G34 = (G24 + G33 + G35 + G44) / 4$$

$$B34 = (B23 + B25 + B43 + B44) / 4 = 0$$

 Green

$$R44 = (R34 + R54) = 0$$

$$G44 = G44$$

$$B44 = (B43 + B44) / 2 = 0$$

 Green